

Gauss Seidel → Method of Successive Replacements

Tuesday, November 19, 2019 12:07 PM

Recall

$$\begin{aligned}2x_1 - x_2 &= 0 \rightarrow (1) \\ -x_1 + 2x_2 - x_3 &= 1 \rightarrow (2) \\ -x_2 + 2x_3 &= 2 \rightarrow (3)\end{aligned}$$

Initial Guess $x^{(0)} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow x^{(1)} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \end{pmatrix}$

Use eqⁿ(1) to update first component $x_1^{(1)}$

(same as Jacobi!)

$$2x_1^{(1)} - x_2^{(0)} = 0 \rightarrow x_1^{(1)} = 0.$$

Use eqⁿ(2) to update the second component $x_2^{(1)}$.
and use freshly calculate $x_1^{(1)} = 0$

$$-x_1^{(1)} + 2x_2^{(1)} - x_3^{(0)} = 1$$

$$x_2^{(1)} = \frac{1}{2}$$

Use eqⁿ(3) to update third component $x_3^{(1)}$.
and use $x_1^{(1)} = 0$ and $x_2^{(1)} = 0.5$.

$$-x_2^{(1)} + 2x_3^{(1)} = 2$$

$$\begin{aligned}x_3^{(1)} &= \frac{1}{2}(2 + 0.5) \\ &= 1.25\end{aligned}$$

$$x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow x_{GS}^{(1)} = \begin{bmatrix} 0 \\ 0.5 \\ 1.25 \end{bmatrix} \dots$$

[0]

[1.25]

See Lecture Slides for another example!

Error Analysis:

Pre Requisites

① $\|Ax\| \leq \|A\| \|x\|$

norm of matrix vector product "smaller than"

PRODUCT OF NORMS OF A AND x

② x^* true solution to $Ax = b$.

$\|x^* - x^{(k)}\| \leq ?$ without any knowledge about x^* !

③ Write the Jacobi & Gauss Seidel method in a compact form:

$Nx^{(k+1)} = b + Px^{(k)}$ $k=0,1,2,\dots$

where

N & P are matrices derived from A such that $P = N - A$.

Before error analysis,

let us derive $Nx^{(k+1)} = b + Px^{(k)}$

for Jacobi & GS (Gauss Seidel) method.

Jacobi Method:

$A = L + U$

Jacobi Method :

$$AX = b$$

$$A = (a_{ij})_{3 \times 3} \quad x \text{ \& b are } 3 \times 1.$$

Given $x^{(0)}$

$$a_{11} \leftarrow x_1^{(1)} = \frac{1}{a_{11}} (b_1 - a_{12}x_2^{(0)} - a_{13}x_3^{(0)})$$

$$a_{22} \leftarrow x_2^{(1)} = \frac{1}{a_{22}} (b_2 - a_{21}x_1^{(0)} - a_{23}x_3^{(0)})$$

$$a_{33} \leftarrow x_3^{(1)} = \frac{1}{a_{33}} (b_3 - a_{31}x_1^{(0)} - a_{32}x_2^{(0)})$$

$$N x^{(k+1)} = b + P x^{(k)} \quad k=0$$
$$N x^{(1)} = b + P x^{(0)}$$

$$N = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix} \quad \text{check } N x^{(1)} = \begin{bmatrix} a_{11}x_1^{(1)} \\ a_{22}x_2^{(1)} \\ a_{33}x_3^{(1)} \end{bmatrix}$$

for Jacobi method,

$N =$ diag matrix with diag. entries a_{11}, a_{22}, a_{33} .

Then

$$P = N - A$$

$$P = \begin{bmatrix} 0 & -a_{12} & -a_{13} \\ -a_{21} & 0 & -a_{23} \\ -a_{31} & -a_{32} & 0 \end{bmatrix}$$

What we have shown: Jacobi method is

$$x^{(k+1)} = \dots = P x^{(k)} \quad k=0,1,\dots$$

What we have shown...

$$N x^{(k+1)} = b + P x^{(k)} \quad k=0,1,\dots$$

given $x^{(0)}$

where $N = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$

$$P = N - A = \begin{bmatrix} 0 & -a_{12} & -a_{13} \\ -a_{21} & 0 & -a_{23} \\ -a_{31} & -a_{32} & 0 \end{bmatrix}$$

Check: $N x^{(k+1)} = b + P x^{(k)}$

focus on RHS

$$b + P x^{(k)}$$

$$= \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} + \begin{bmatrix} 0 & -a_{12} & -a_{13} \\ -a_{21} & 0 & -a_{23} \\ -a_{31} & -a_{32} & 0 \end{bmatrix} \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ x_3^{(k)} \end{bmatrix}$$

$$= \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} + \begin{bmatrix} -a_{12}x_2^{(k)} - a_{13}x_3^{(k)} \\ -a_{21}x_1^{(k)} - a_{23}x_3^{(k)} \\ -a_{31}x_1^{(k)} - a_{32}x_2^{(k)} \end{bmatrix}$$

DUC for Jacobi formula

RHS for Jacobi formula

$$NX^{(k+1)} = \begin{bmatrix} a_{11} x_1^{(k+1)} \\ a_{22} x_2^{(k+1)} \\ a_{33} x_3^{(k+1)} \end{bmatrix}$$

For Gauss Seidel,

$$NX^{(k+1)} = b + PX^{(k)}$$

What are N & P?

$$P = N - A$$

GS formula: Given $x^{(0)}$:

$$x_1^{(1)} = \frac{1}{a_{11}} (b_1 - a_{12} x_2^{(0)} - a_{13} x_3^{(0)})$$

$$\textcircled{1} \quad a_{11} x_1^{(1)} = b_1 - a_{12} x_2^{(0)} - a_{13} x_3^{(0)}$$

$$a_{21} x_1^{(1)} + a_{22} x_2^{(1)} = b_2 - a_{23} x_3^{(0)} \quad \textcircled{2}$$

$$\textcircled{3} \quad a_{31} x_1^{(1)} + a_{32} x_2^{(1)} + a_{33} x_3^{(1)} = b_3$$

$$NX^{(k+1)} = b + PX^{(k)}$$

$$\begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \end{bmatrix} \stackrel{\text{check}}{=} \begin{bmatrix} a_{11} x_1^{(1)} \\ a_{21} x_1^{(1)} + a_{22} x_2^{(1)} \\ a_{31} x_1^{(1)} + a_{32} x_2^{(1)} + a_{33} x_3^{(1)} \end{bmatrix}$$

$$\begin{bmatrix} a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_3^{(k)} \end{bmatrix} \quad \begin{bmatrix} a_{31}x_1^{(k)} + a_{32}x_2^{(k)} + \\ a_{33}x_3^{(k)} \end{bmatrix}$$

exactly the LHS of ①, ② & ③.

$$N = \begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$P = N - A = \begin{bmatrix} 0 & -a_{12} & -a_{13} \\ 0 & 0 & -a_{23} \\ 0 & 0 & 0 \end{bmatrix}$$

What we have achieved:

GS formula:

$$\text{given } x^{(0)}, \quad N x^{(k+1)} = b + P x^{(k)} \quad k=0,1,\dots$$

N = Lower triangular part of A including diag. entries

$$= \begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$P = N - A = \begin{bmatrix} 0 & -a_{12} & -a_{13} \\ 0 & 0 & -a_{23} \\ 0 & 0 & 0 \end{bmatrix}.$$

Notation

N_{GS} & P_{GS} denote GS method
 N_J & P_J), Jacobi method.

Lecture Slides.

Lecture Slides.

Coming to the Point: Error Analysis!

$$N x^{(k+1)} = b + P x^{(k)}$$

Error Analysis works for any iterative method than can be expressed using N & P .

example: III / HWK05 The error analysis is valid for:

we have $x^{(k+1)} = b + M x^{(k)}$

with $M = \begin{bmatrix} \alpha & \beta \\ -\beta & \alpha \end{bmatrix}$

$$N x^{(k+1)} = b + P x^{(k)}$$

$$N = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad P = \begin{bmatrix} \alpha & \beta \\ -\beta & \alpha \end{bmatrix}.$$

Let $N x^{(k+1)} = b + P x^{(k)}$ denote an iterative formula for any $x^{(0)}$ for approximating x^* (x^* is the true solution to $Ax = b$).
(unknown)

Then, the iterative formula converges provided $\|N^{-1}P\| < 1$.

FURTHERMORE:

$$\|x^* - x^{(k+1)}\| \leq \|N^{-1}P\|^{k+1} \|x^* - x^{(0)}\|$$

$$\|x^* - x^{(k+1)}\| \leq \|N^{-1}P\| \|x^* - x^k\|$$

HWK 05

$$A_n = \begin{bmatrix} 1 & -1 & \dots & -1 \\ 0 & \dots & 0 & 1 \end{bmatrix}$$

Given $\rightarrow A_n$

$$A_n = \text{Identity}(n)$$

for i
for j