

(1,1) (4,2) (9,3) 3 data points → deg 2 poly

$$P_2(x) = 1 * \frac{(x-4)(x-9)}{(1-4)(1-9)} + 2 * \frac{(x-1)(x-9)}{(4-1)(4-9)} + 3 * \frac{(x-1)(x-4)}{(9-1)(9-4)}$$

$$P_2(x) = y_0 l_0(x) + y_1 l_1(x) + y_2 l_2(x)$$

check:

$$P_2(1) = 1 * \frac{(1-4)(1-9)}{(1-4)(1-9)} + 0 = 1 \checkmark$$

$$P_2(4) = 0 + 2 * \frac{(4-1)(4-9)}{(4-1)(4-9)} = 2 \checkmark$$

$$P_2(9) = 0 + 3 * \frac{(9-1)(9-4)}{(9-1)(9-4)} = 3 \checkmark$$

$P_2(x)$ interpolated (1,1) (4,2) & (9,3).
 What happens if I add one more data point? (16,4)

$(x_0, y_0) \dots (x_3, y_3)$
 $(1,1) (4,2) (9,3) \& (16,4)$

the Lagrange formula needs to be redone!

$$P_3(x) = y_0 l_0(x) + y_1 l_1(x) + y_2 l_2(x) + y_3 l_3(x)$$

$$P_3(x) = 1 * \frac{(x-4)(x-9)(x-16)}{(1-4)(1-9)(1-16)} +$$

$$2 * \frac{(x-1)(x-9)(x-16)}{(4-1)(4-9)(4-16)} +$$

$$3 * \frac{(x-1)(x-4)(x-16)}{(9-1)(9-4)(9-16)} +$$

$$4 * \frac{(x-1)(x-4)(x-9)}{(16-1)(16-4)(16-9)}$$

Disadvantage of Lagrange: every time a new data point is added, the whole poly. needs to be reconstructed!

Newton's Divided Difference poly. formula overcomes this!

How?

D.D (Divided Difference) of a function $f(x)$

$$f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

Newton's Quotient Slope



Newton's D.D of order 1

$$f[x_i, x_{i+1}] = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i}$$

Note: $x_{i+1} = x_i + \Delta x$

$$f[x_i, x_{i+1}] = \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x} \approx f'(x_i)$$

$$\lim_{\Delta x \rightarrow 0} \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x} = f'(x_i)$$

$P_1^N(x)$ = Newton's D.D poly interpolating (x_0, y_0) (x_1, y_1)

$$= f(x_0) + f[x_0, x_1] (x - x_0)$$

$$= f(x_0) + \left(\frac{f(x_1) - f(x_0)}{x_1 - x_0} \right) (x - x_0)$$

for (1,1) & (4,2) the Newton's D.D poly is:

$$P_1^N(x) = 1 + f[1,4] (x-1)$$

$$= 1 + \frac{2-1}{4-1} (x-1)$$

$$\begin{aligned}
 P_1^N(x) &= 1 + f[1,4](x-1) \\
 &= 1 + \frac{(2-1)}{4-1}(x-1) \\
 &= 1 + \frac{(x-1)}{3}
 \end{aligned}$$

Check: $P_1^N(1) = 1$ ✓ $P_1^N(4) = 1 + \frac{(4-1)}{3} = 1+1=2$ ✓

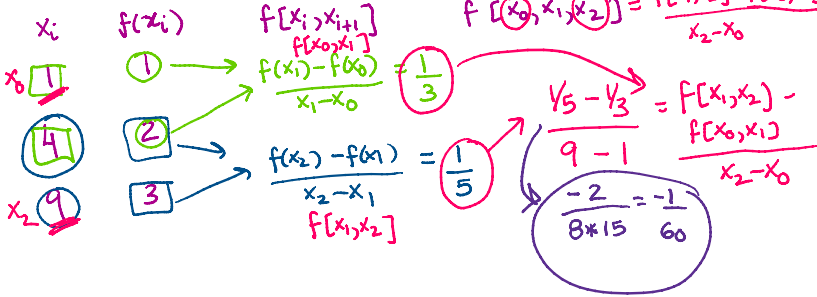
Newton's D.D poly for $f(x)$?
 $(1,1)$ $(4,2)$ $(9,3)$?

3 data points need deg 2 poly.

$$P_2^N(x) = f(x_0) + f[x_0, x_1](x-x_0) + f[x_0, x_1, x_2](x-x_0)(x-x_1)$$

D.D of order 2 w.r.t $f(x)$

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$$



$$P_2^N(x) = 1 + \frac{(x-1)}{3} + \left(-\frac{1}{60}\right)(x-1)(x-4)$$

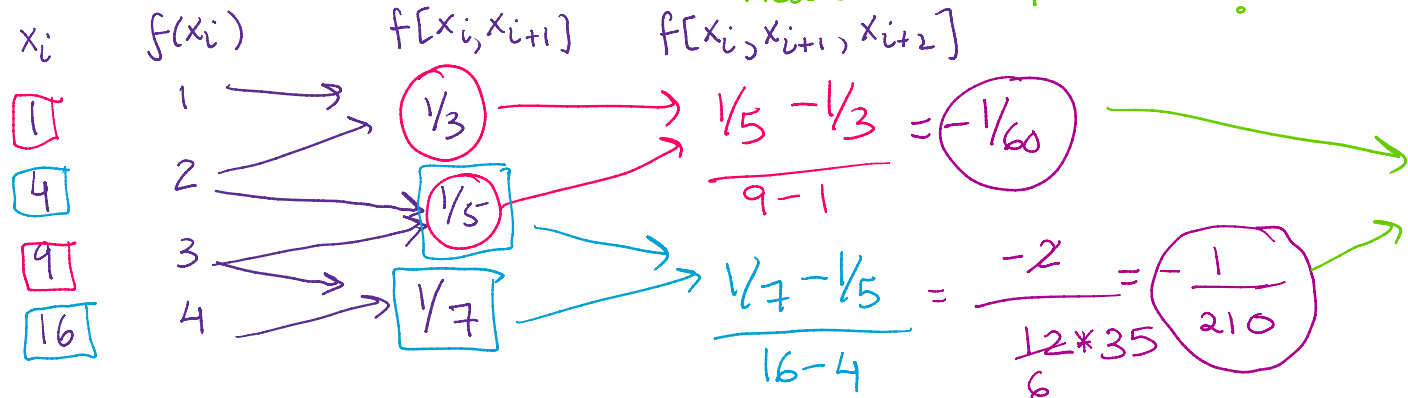
check: $P_2^N(1) = 1$, $P_2^N(4) = 2$ & $P_2^N(9) = 3$.

Construct the Newton's D.D poly interpolating
 $(1,1)$, $(4,2)$, $(9,3)$ & $(16,4)$.

4 data points \Rightarrow use $P_3^N(x)$

$$\begin{aligned}
 P_3^N(x) &= f(x_0) + f[x_0, x_1](x-x_0) + f[x_0, x_1, x_2](x-x_0)(x-x_1) \\
 &\quad + f[x_0, x_1, x_2, x_3](x-x_0)(x-x_1)(x-x_2)
 \end{aligned}$$

Newton's D.D of order 3!



$$\begin{aligned}
 &f[x_0, x_1, x_2, x_3] \\
 &= \frac{-1/210 + \dots}{16 - \dots} \\
 &= \frac{-60 + \dots}{15}
 \end{aligned}$$

$-, x_3]$

$$\frac{1/60}{x_0} = 0.007365$$

$$\frac{210}{5 * 210 * 60} = \frac{10}{15 * 210 * 60}$$

$\frac{1}{1}$

$$p_3^N(x) = 1 + \frac{(x-1)}{3} - \frac{(x-1)(x-4)}{60} + \frac{1}{1260} (x-1)(x-4)$$

$$= 1 + (x-1) \left(\frac{1}{3} + (x-4) \left(-\frac{1}{60} + \frac{1}{1260} \right) \right)$$

Horner's Scheme (Nester)

Disadvantage of Newton's D.D poly:

Error formula is in an impractical

Work Around: poly interpolates $n+1$ distinct
is always unique!

$$P_n^L(x) = P_n^N(x)$$

for interpolating $(x_0, y_0), \dots, (x_n, y_n)$

so we use the "nice" Lag poly error formula instead!

BOT
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T
dis

$$5 * 210 * 60$$

$$(x-9)$$

$$= \frac{1}{1260}$$

$$\left. \begin{array}{l} x-9 \\ \hline 1260 \end{array} \right\} \text{d Approach}$$

form!
points

WITH LAGRANGE &
NEWTON POLY GIVE
THE SAME CURVE
distinct
points!
representation